

Multi-Core Computing with Transactional Memory





Overview

- Introduction
- Difficulties with parallel (multi-core) programming
- A (partial) solution: Transactional Memory
- Contention Management



Multi-cores will be everywhere

- To increase computing speed, traditionally the clock speed of a CPU was increased
 - Problem: Overheating
- New approach: Have many cores on a single die
- Multi-core chips are used in every PC and soon in every mobile phone
- It is likely that we see a doubling of cores every 2 years like we saw a doubling of clock speed
- BUT: Parallel programming brings new problems and adds complexity for software engineers









Why is parallel programming more difficult?

- We need synchronization...
 - Parallel reservation system for cinema tickets without synchronization

Time	Thread 1 - Return 5 tickets	n = Number of sold tickets	Thread 2 - Buy 3 tickets
0		100	
1	Read n (Return 100)	100	
2		100	Read n (Return 100)
3	New value for n: 100-5 =95 Set n to 95	95	
4		103	New value for n: 100+3=103 Set n to 103





Two kinds of parallelism

- Data parallelism
 - different data for each thread (running on a core)
 - every core works separately
 - No overlapping, no problem!
 - Ex.: Each thread sorts a given set of data unknown to other threads

Task parallelism

- several tasks working on same/overlapping data
- Ex.: All threads insert/delete elements in the same tree

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Concurrent programming today

- Synchronization using locks or monitors
 - Locks implemented via test-and-set or compare and swap operations
 - Monitor : Mutual exclusion
 - e.g. java "synchronized method"
 - Easy but slow -> only 1 thread runs at a time
- Coarse grained vs. fine grained locking easy but slow program Little(no) parallelism

lock all data modify/use data unlock all data

Only 1 thread can operate on the data

difficult, cumbersome but fast programs lots of code, deadlocks...





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Example: Deleting an element from a linked list

- Sequential code/Coarse grained locking
 < 10 lines of code
- Concurrent linked list: See below...

The List::delete method attempts to remove a node containing the supplied key.

```
private Node *List::search (KeyType search_key, Node **left_node) {
public boolean List::delete (KeyType search_key) {
                                                                             Node *left_node_next, *right_node;
 Node *right_node, *right_node_next, *left_node;
                                                                           search_again:
 do {
                                                                             do {
   right_node = search (search_key, &left_node);
                                                                               Node *t = head:
   if ((right_node == tail) || (right_node.key != search_key)) /*T1*/
                                                                               Node *t_next = head.next;
     return false;
   right_node_next = right_node.next;
                                                                               /* 1: Find left_node and right_node */
   if (!is_marked_reference(right_node_next))
                                                                               do {
     if (CAS (&(right_node.next), /*C3*/
                                                                                 if (!is_marked_reference(t_next)) {
          right_node_next, get_marked_reference (right_node_next)))
                                                                                   (*left_node) = t;
        break:
                                                                                   left_node_next = t_next;
 } while (true); /*B4*/
  if (!CAS (&(left_node.next), right_node, right_node_next)) /*C4*/
                                                                                 t = get_unmarked_reference(t_next);
   right_node = search (right_node.key, &left_node);
                                                                                 if (t == tail) break;
 return true:
                                                                                 t_next = t.next;
3
                                                                               } while (is_marked_reference(t_next) || (t.key<search_key)); /*B1*/</pre>
                                                                               right_node = t;
                                                                               /* 2: Check nodes are adjacent */
                                                                               if (left_node_next == right_node)
                                                                                 if ((right_node != tail) && is_marked_reference(right_node.next))
                                                                                   goto search_again; /*G1*/
                                                                                 else
                                                                                   return right_node; /*R1*/
                                                                               /* 3: Remove one or more marked nodes */
                                                                               if (CAS (&(left_node.next), left_node_next, right_node)) /*C1*/
                                                                                 if ((right_node != tail) && is_marked_reference(right_node.next))
                                                                                   goto search_again; /*G2*/
                                                                                 else
                                                                                   return right_node; /*R2*/
                                                                             } while (true); /*B2*/
```





More problems with locking - Composability

- How to compose objects/components using locks
- If locks are external then programmer must handle locking himself
 - cumbersome(lots of code), error-prone (deadlocks)
- If locks are internal then it is not possible to achieve all desired behaviors
 - Example: Hash table T1 (contains number 1) and T2 (empty) No duplicates, each element unique

2 threads moving elements between tables

```
Algorithm Move(Element e, Table from, Table to)
if from.find(e) then
to.insert(e)
from.delete(e)
end if
```





Example continued...

Threads might be delayed for some reasons: interrupts, cache miss...

	Table T1 contains 1 and T2 is empty	
Time	Thread 1	Thread 2
	Move(1,T1,T2)	Move(1,T2,T1)
1	T1.find(1)	delayed
2	T2.insert(1)	
3	delayed	T2.find(1)
4		T1.insert(1)
5	T1.delete(1)	T2.delete(1)
	both T1 and T2 are empty	

• Where is the '1'?



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Transactional memory(TM) - a (partial) solution

Simple for the programmer

Begin transaction modify/use data End transaction

omnosable	Algorithm Move(Element e, Table from, Table to) Begin Transaction		
omposable	if from.find(e) then End Transaction	Method Table.find(Element e) Begin transaction	
		End transaction	

- Many TM systems (internally) still use locks
- But the TM system (not the programmer) cares about
 - Performance
 - Progress/correctness (no deadlocks...)





What is a transaction?

- Nothing new, has been used in databases for a long time
- Characterized by 3 properties (ACI)
 - Atomicity
 - Either a transaction finishes all its operations or no operation has an effect on the system
 - Consistency
 - All objects are in a valid state before and after the transaction
 - Isolation
 - A transaction cannot access or see data in an intermediate (possibly invalid) state of any parallel running transactions.
- For databases also durability
 - If a transaction has completed, its changes are permanent
 - Written on a disk not just in memory





Implementation of a TM system

- Systems exist in hardware, software and as a mix (hybrid)
- (Usually) transactions are executed optimistically
 - i.e. without knowing whether they use the same data
- If transactions work on
 - different data, everything is ok
 - modify the same data, conflicts arise that must be resolved...
 - Transactions might get delayed (has to wait) or aborted.
- A transaction keeps track of all modified values and restores all values, if it is aborted due to a conflict.
- A transaction successfully finishes with a commit
 Only after the commit, other transactions notice its changes.





Conflicts – A contention manager decides

- A contention manager can abort or delay a transaction
- Important impact on performance
- Example
 - Initially: A=1, B=1









Just another example of a contention manager







Why is TM only a partial solution? – Open issues

- I/O support
 - Imagine a document is printed within a transaction and the transaction gets aborted => waste of paper
- Interaction with old, non-transactional (legacy) code
- Efficiency
 - TM still too slow, but catching up quickly...
- Despite the problems:
 - TM system already on the market, partially supporting hardware TM
 - many software TM libraries exist





Open issues from a research perspective

• Why research?

- Help understanding to improve efficiency
- create (provable) secure systems
- System model not sufficient

 PRAM: assumes threads are synchronous only read/write access to memory (e.g. no test and set)

no multilevel caching



- How to resolve conflicts?
 - What is the 'best' contention manager?





Some theory on contention management

- Model: *n* transactions (and threads) starting concurrently on *n* cores
- S (shared) resources (variables/objects)
- Transaction = sequence of operations
- Operation:
 - takes 1 time unit
 - 2 kinds: Write, compute/abort/commit
 - Write = modify (shared) resource and lock it until commit
- A conflict arises if transaction A wants to lock a resource that is already locked by B





Model continued...

- A transaction demands unknown resources
 - Dynamic data structures change over time
 - Eg.:Binary tree, a transaction wants to insert 3

Initially: Must lock/modify right pointer of node 1

Assume transaction got aborted and another transaction inserted 4 meanwhile.

Now: Must lock/modify left pointer of node 4

- Duration(number of operations) is fixed
 - Not true, but mostly only a constant factor away
- Model is a simplification
 - Ex.: There are also reads
 - Ex.: a write access, does not always require a resource to be locked







Contention manager (CM)

- Distributed
 - Each thread has its own manager
- Does not know future(potential) conflicts
 - Conflicts also not learnable, might change
 - Online scheduling problem







Properties of a contention manager

- Throughput
 - Makespan = How long it takes until all n transactions committed = length of a schedule
 - Schedule of transactions defined by decisions of CM
 - Look at worst case
 - Competitive ratio = makespan my CM / makespan optimal CM
 - Oblivious adversary = knows my CM (not random choices)
 - Optimal CM knows decisions of adversary and all conflicts...
- Progress guarantees
 - wait freedom (strongest guarantee)
 - all threads(transactions) make progress in a finite number of steps
 - Iock freedom
 - one thread makes progress in a finite number of steps
 - obstruction freedom (weakest)
 - a thread makes progress in a finite number of steps in absence of contention (no conflicts, no shared data)





Example of a CM

- Strategy: Be aggressive
 - If a transaction A wants a resource locked by B, then B is aborted
- Throughput?
 - (Possibly) none
 - Livelock: Transactions repeatedly abort each other
 - Eg: 2 Transactions that write/lock the same resource



- Progress guarantees?
 - Obstruction freedom





T2

Problem complexity, it is (NP) hard...

- How long does it take to compute a good schedule?
 - = Is it NP-hard to approximate the optimal makespan by a constant factor?
 - ...as long as approximating an optimal vertex coloring
 - Optimal = Minimum number of colors = $\chi(G)^{\frac{\log \chi(G)}{25}}$
 - NP-hard to compute a coloring with
- Reduction to coloring
 - Graph -> Scheduling problem -> Schedule -> Coloring
 - Nodes = transactions
 - Edges = resources (conflicts)
 - Transactions have same duration t (=1)
 - Transactions of same color don't conflict

T3 T7 Time [0,t] [t,2t] [2t,3t] T1,T2,T3 T4.T5.T6 **T7, T8** Trans. Run&commit

Τ4

R14

 $\chi(G)$

R17

Τ1

if resource acquisition takes almost no time, otherwise more complex

This holds even, if all transactions (potential) conflicts are known and transactions don't change





It is hard, so what can be done? Another example...

CM Strategy: Avoid wasting work

- Approximate the work done
- Each transaction gets a (unique) timestamp t on startup (and after an abort)
- Conflict: The younger transaction, having performed less work, is aborted
- Throughput? Progress guarantees?
 - Oldest transaction will always commit
 - Lock freedom
 - At least one out of n cores successfully executes a transaction







Competitive ratio of the time stamp manager

- S resources
- n transactions that start concurrently
- Assume each transaction T_i locks a resource directly after its start for its whole duration t_{Ti}
- Observe: At most S transactions can run in parallel
 - If S+1 run in parallel at least 2 must attempt to lock the same resource
- Thus the optimal makespan is at least:
- Makespan CM timestamp is at most:
 all run sequentially in the worst case
- Competitive ratio = timestamp/ optimal

 $\sum_{i=0}^{n} \frac{t_{T_i}}{s}.$ $\sum_{i=0}^{n} t_{T_i}$

$$\frac{\sum_{i=0}^{n} t_{T_i}}{\sum_{i=0}^{n} \frac{t_{T_i}}{s}} = s = \Omega(s)$$





Aborted Trans.

R0:=1

Lower bound on competitive ratio

- Thm: Competitive ratio of any CM (deterministic and randomized) is Ω(n) if number of resources S >= n
- Proof (only for deterministic CM)



- Any CM must abort $\frac{1}{2}$ of all transactions S_T , say S_A
- Adversary knows the aborted trans. S_A
- She/he lets all of them lock the same resource R0
- All aborted transaction (½ n) must run sequentially
- Optimal lets all transactions S_A commit and aborts the other $\frac{1}{2}$

Aborted Trans.

R0:=1





Analysis of algorithm timestamp revisited

- For the lower bound the adversary reduced the parallelism dramatically
 - This is unlikely to happen
- Assume the demanded resources don't change over time
 i.e. the adversary cannot reduce parallelism at run-time
- Is the competitive ratio still Ω(n) (for S>=n)?
 - Yes (proof next slide)
 - All transactions start concurrently
 - Adversary knows timestamps of all transactions









Proof continued...

- Transaction Ti (>1) aborts at time n-i+1, Trans. 1 commits
- After a restart Transaction Ti (>2) aborts after running for time n-i+2, Trans. 2 commits
- After the next restart Transaction Ti (>3) aborts after running for time n-i+3, Trans. 3 commits
- The time until transaction i=n commits is $\sum_{i=1}^{n} (n-i) = \Omega(n^2)$
- Optimal:
 - Schedules all transaction Ti with even i then the rest
 - O(n)
- Competitive ratio: Ω(n)





How about a randomized approach?

- Choose a random priority r from [1,n] on startup
- Transaction A with larger or same random number wins conflict against B
 - B aborts and waits
 - Restart with a new random number as soon as A either commits or aborts





Analysis

- Assume:
 - (needed) resources are not modified
 - Longest transaction takes time t
 - Any transaction conflicts with at most **d** other transactions
- After time 2 t any transaction can restart and draw a new random number
 - Execute for time t-1 and then aborts and wait for at most time t
- Probability highest rand. number: 1/d
- Prob. random number unique: $(1 1/n)^{d} < (1 1/n)^n \approx 1/e$
- Choose *d e* log *n* random numbers and probability to commit is: $1 - (1 - \frac{1}{e \cdot d})^{e \cdot d - \log n} \approx 1 - \frac{1}{e}^{\log n} = 1 - \frac{1}{n}$





Analysis continued and evaluation

Time to choose d e log n random numbers is O(t d log n)

How good is the algorithm?

- For the analysis of algorithm timestamp d = 2, t = n
 - Makespan of randomized CM: O(n log n) with 'high' probability
 - Deterministic timestamp: O(n²)
- Complexity measure
 - Originally: Dependent on number of resources
 - Now: Dependent on number of conflicts a transaction faces
 - Better?





Theory and practice

- For most benchmarks our randomized approach and a timestamp manager achieve comparable throughput
- In general, the quality of a CM varies very much across different benchmarks
 - A CM might be good for one benchmark but bad for another
- A strategy that is (often) good:
 - After a conflict do some kind of exponential randomized backoff
 - Reduces load on system, resolves livelocks





Exponential backoff

- Example: Polka manager
 - Approximate work: priority = number of accessed resources
 - In case of a conflict: If have higher priority abort the other, if have lower priority, then perform an exponential backoff
 - Say priority difference of the two transactions is r
 - Algorithm:

For *i* = 0..*r*

If resource not locked then lock it

else wait random time span with mean 2'

After *r* unsuccessful trials abort transaction with higher priority



Semester/master theses

- Check the homepage
 - www.dcg.ethz.ch/theses.html





- For TM: Currently, more practical theses
 - Programming, but challenging programming...
 - Focus improve speed
 - Speeding up programs (on multi-core systems)
 - Efficient Multicore Systems with Transactional Memory



That's it, have a nice vacation!

